

### FEATURES

- Low offset voltage: 2.5  $\mu\text{V}$  maximum
- Low offset voltage drift: 0.015  $\mu\text{V}/^\circ\text{C}$  maximum
- Low noise
  - 5.6  $\text{nV}/\sqrt{\text{Hz}}$  at  $f = 1 \text{ kHz}$ ,  $A_V = +100$
  - 97  $\text{nV p-p}$  at  $f = 0.1 \text{ Hz to } 10 \text{ Hz}$ ,  $A_V = +100$
- Open-loop gain: 130 dB minimum
- CMRR: 135 dB minimum
- PSRR: 130 dB minimum
- Unity-gain crossover: 4 MHz
- Gain bandwidth product: 3 MHz at  $A_V = 100$
- 3 dB closed-loop bandwidth: 6.2 MHz
- Single-supply operation: 2.2 V to 5.5 V
- Dual-supply operation:  $\pm 1.1 \text{ V to } \pm 2.75 \text{ V}$
- Rail-to-rail input and output
- Unity-gain stable

### APPLICATIONS

- Thermocouple/thermopile
- Load cell and bridge transducers
- Precision instrumentation
- Electronic scales
- Medical instrumentation
- Handheld test equipment

### GENERAL DESCRIPTION

The ADA4528-1/ADA4528-2 are ultralow noise, zero-drift operational amplifiers featuring rail-to-rail input and output swing. With an offset voltage of 2.5  $\mu\text{V}$ , offset voltage drift of 0.015  $\mu\text{V}/^\circ\text{C}$ , and typical noise of 97  $\text{nV p-p}$  (0.1 Hz to 10 Hz,  $A_V = +100$ ), the ADA4528-1/ADA4528-2 are well suited for applications in which error sources cannot be tolerated.

The ADA4528-1/ADA4528-2 have a wide operating supply range of 2.2 V to 5.5 V, high gain, and excellent CMRR and PSRR specifications, which make it ideal for applications that require precision amplification of low level signals, such as position and pressure sensors, strain gages, and medical instrumentation.

The ADA4528-1/ADA4528-2 are specified over the extended industrial temperature range ( $-40^\circ\text{C}$  to  $+125^\circ\text{C}$ ). The ADA4528-1 is available in 8-lead MSOP and 8-lead LFCSP packages. The ADA4528-2 is available in an 8-lead MSOP package.

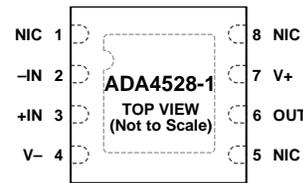
For more information about the ADA4528-1/ADA4528-2, see the AN-1114 Application Note, *Lowest Noise Zero-Drift Amplifier Has 5.6  $\text{nV}/\sqrt{\text{Hz}}$  Voltage Noise Density*.

### PIN CONNECTION DIAGRAMS



NOTES  
1. NIC = NO INTERNAL CONNECTION.

Figure 1. ADA4528-1 Pin Configuration, 8-Lead MSOP



NOTES  
1. NIC = NO INTERNAL CONNECTION.  
2. CONNECT THE EXPOSED PAD TO V- OR LEAVE IT UNCONNECTED.

Figure 2. ADA4528-1 Pin Configuration, 8-Lead LFCSP

For ADA4528-2 pin connections and for more information about the pin connections for these products, see the Pin Configurations and Function Descriptions section.

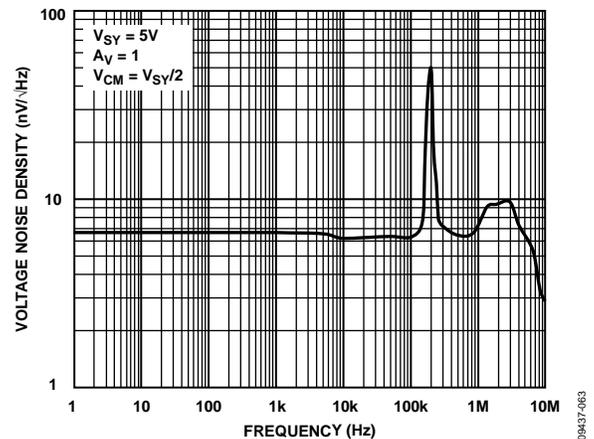


Figure 3. Voltage Noise Density vs. Frequency

Table 1. Analog Devices, Inc., Zero-Drift Op Amp Portfolio<sup>1</sup>

Type	Ultralow Noise	Micropower (<20 $\mu\text{A}$ )	Low Power (<1 mA)	16 V Operating Voltage	30 V Operating Voltage
Single	ADA4528-1	ADA4051-1	AD8628 AD8538	AD8638	ADA4638-1
Dual	ADA4528-2	ADA4051-2	AD8629 AD8539	AD8639	
Quad			AD8630		

<sup>1</sup> See [www.analog.com](http://www.analog.com) for the latest selection of zero-drift operational amplifiers.

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**REVISION HISTORY**

**9/12—Rev. B to Rev. C**

Changes to Features Section..... 1  
 Added Comparator Operation Section ..... 21  
 Added Figure 65 to Figure 69; Renumbered Sequentially ..... 21

**7/12—Rev. A to Rev. B**

Added [ADA4528-2](#)..... Universal  
 Changes to Features Section, Figure 1, Figure 2, and Table 1 .... 1  
 Added Pin Connection Diagrams Section and Figure 3;  
 Renumbered Sequentially..... 1  
 Changes to Table 2..... 3  
 Changes to Table 3..... 5  
 Change to Endnote 1 of Table 4 and Thermal Resistance  
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 Added Pin Configurations and Function Descriptions Section,  
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 Added Figure 6 and Table 7..... 9  
 Changes to Input Protection Section ..... 19  
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 Caption of Figure 63..... 20

Changes to Residual Voltage Ripple Section and

Caption of Figure 64..... 21  
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**9/11—Rev. 0 to Rev. A**

Added 8-Lead LFCSP\_WD Package..... Universal  
 Changes to General Description Section .....1  
 Added Figure 2; Renumbered Sequentially .....1  
 Changes to Offset Voltage, Offset Voltage Drift, Power Supply  
 Rejection Ratio, and Settling Time to 0.1% Parameters, Table 2...3  
 Changes to Thermal Resistance Section and Table 5 .....5  
 Changes to Figure 41 and Figure 44 ..... 12  
 Changes to Figure 45 and Figure 48 ..... 13  
 Updated Outline Dimensions ..... 18  
 Changes to Ordering Guide ..... 18

**1/11—Revision 0: Initial Version**

## SPECIFICATIONS

## ELECTRICAL CHARACTERISTICS—2.5 V OPERATION

$V_{SY} = 2.5 \text{ V}$ ,  $V_{CM} = V_{SY}/2$ ,  $T_A = 25^\circ\text{C}$ , unless otherwise specified.

Table 2.

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
INPUT CHARACTERISTICS						
Offset Voltage	$V_{OS}$	$V_{CM} = 0 \text{ V to } 2.5 \text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , MSOP package $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , LFCSP package		0.3	2.5	$\mu\text{V}$ $\mu\text{V}$
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , MSOP package $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$ , LFCSP package		0.002	0.015	$\mu\text{V}/^\circ\text{C}$ $\mu\text{V}/^\circ\text{C}$
Input Bias Current	$I_B$	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		220	400	$\text{pA}$ $\text{pA}$
Input Offset Current	$I_{OS}$	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		440	800	$\text{pA}$ $\text{nA}$
Input Voltage Range			0		2.5	$\text{V}$
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0 \text{ V to } 2.5 \text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	135	158		$\text{dB}$ $\text{dB}$
Open-Loop Gain	$A_{VO}$	$R_L = 10 \text{ k}\Omega$ , $V_O = 0.1 \text{ V to } 2.4 \text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	130	140		$\text{dB}$ $\text{dB}$
<a href="#">ADA4528-1</a>		$R_L = 2 \text{ k}\Omega$ , $V_O = 0.1 \text{ V to } 2.4 \text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	125	132		$\text{dB}$ $\text{dB}$
<a href="#">ADA4528-2</a>		$R_L = 2 \text{ k}\Omega$ , $V_O = 0.1 \text{ V to } 2.4 \text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	122	132		$\text{dB}$ $\text{dB}$
Input Resistance						
Differential Mode	$R_{INDM}$			225		$\text{k}\Omega$
Common Mode	$R_{INCM}$			1		$\text{G}\Omega$
Input Capacitance						
Differential Mode	$C_{INDM}$			15		$\text{pF}$
Common Mode	$C_{INCM}$			30		$\text{pF}$
OUTPUT CHARACTERISTICS						
Output Voltage High	$V_{OH}$	$R_L = 10 \text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	2.49	2.495		$\text{V}$ $\text{V}$
		$R_L = 2 \text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	2.46	2.48		$\text{V}$ $\text{V}$
Output Voltage Low	$V_{OL}$	$R_L = 10 \text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		5	10	$\text{mV}$ $\text{mV}$
		$R_L = 2 \text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		20	40	$\text{mV}$ $\text{mV}$
Short-Circuit Current	$I_{SC}$			$\pm 30$		$\text{mA}$
Closed-Loop Output Impedance	$Z_{OUT}$	$f = 1 \text{ kHz}$ , $A_V = +10$		0.1		$\Omega$
POWER SUPPLY						
Power Supply Rejection Ratio	PSRR	$V_{SY} = 2.2 \text{ V to } 5.5 \text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	130	150		$\text{dB}$ $\text{dB}$
Supply Current per Amplifier	$I_{SY}$	$I_O = 0 \text{ mA}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		1.4	1.7	$\text{mA}$ $\text{mA}$
DYNAMIC PERFORMANCE						
Slew Rate	SR	$R_L = 10 \text{ k}\Omega$ , $C_L = 100 \text{ pF}$ , $A_V = +1$		0.45		$\text{V}/\mu\text{s}$
Settling Time to 0.1%	$t_s$	$V_{IN} = 1.5 \text{ V step}$ , $R_L = 10 \text{ k}\Omega$ , $C_L = 100 \text{ pF}$ , $A_V = -1$		7		$\mu\text{s}$
Unity-Gain Crossover	UGC	$V_{IN} = 10 \text{ mV p-p}$ , $R_L = 10 \text{ k}\Omega$ , $C_L = 100 \text{ pF}$ , $A_V = +1$		4		$\text{MHz}$
Phase Margin	$\Phi_M$	$V_{IN} = 10 \text{ mV p-p}$ , $R_L = 10 \text{ k}\Omega$ , $C_L = 100 \text{ pF}$ , $A_V = +1$		57		Degrees
Gain Bandwidth Product	GBP	$V_{IN} = 10 \text{ mV p-p}$ , $R_L = 10 \text{ k}\Omega$ , $C_L = 100 \text{ pF}$ , $A_V = +100$		3		$\text{MHz}$
-3 dB Closed-Loop Bandwidth	$f_{-3dB}$	$V_{IN} = 10 \text{ mV p-p}$ , $R_L = 10 \text{ k}\Omega$ , $C_L = 100 \text{ pF}$ , $A_V = +1$		6.2		$\text{MHz}$
Overload Recovery Time		$R_L = 10 \text{ k}\Omega$ , $C_L = 100 \text{ pF}$ , $A_V = -10$		50		$\mu\text{s}$

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
NOISE PERFORMANCE						
Voltage Noise	$e_n$ p-p	$f = 0.1 \text{ Hz to } 10 \text{ Hz}, A_v = +100$		97		nV p-p
Voltage Noise Density	$e_n$	$f = 1 \text{ kHz}, A_v = +100$		5.6		nV/ $\sqrt{\text{Hz}}$
		$f = 1 \text{ kHz}, A_v = +100, V_{CM} = 2.0 \text{ V}$		5.5		nV/ $\sqrt{\text{Hz}}$
Current Noise	$i_n$ p-p	$f = 0.1 \text{ Hz to } 10 \text{ Hz}, A_v = +100$		10		pA p-p
Current Noise Density	$i_n$	$f = 1 \text{ kHz}, A_v = +100$		0.7		pA/ $\sqrt{\text{Hz}}$

**ELECTRICAL CHARACTERISTICS—5 V OPERATION**

$V_{SY} = 5\text{ V}$ ,  $V_{CM} = V_{SY}/2$ ,  $T_A = 25^\circ\text{C}$ , unless otherwise specified.

**Table 3.**

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
<b>INPUT CHARACTERISTICS</b>						
Offset Voltage	$V_{OS}$	$V_{CM} = 0\text{ V to } 5\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		0.3	2.5	$\mu\text{V}$
Offset Voltage Drift	$\Delta V_{OS}/\Delta T$	$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		0.002	0.015	$\mu\text{V}/^\circ\text{C}$
Input Bias Current	$I_B$					
ADA4528-1		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		90	200	pA
ADA4528-2		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		125	300	pA
Input Offset Current	$I_{OS}$					
ADA4528-1		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		180	400	pA
ADA4528-2		$-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		250	500	pA
Input Voltage Range			0		5	V
Common-Mode Rejection Ratio	CMRR	$V_{CM} = 0\text{ V to } 5\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	137	160		dB
Open-Loop Gain	$A_{VO}$	$R_L = 10\text{ k}\Omega$ , $V_O = 0.1\text{ V to } 4.9\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	127	139		dB
		$R_L = 2\text{ k}\Omega$ , $V_O = 0.1\text{ V to } 4.9\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	125			dB
			121	131		dB
			120			dB
Input Resistance						
Differential Mode	$R_{INDM}$			190		k $\Omega$
Common Mode	$R_{INCM}$			1		G $\Omega$
Input Capacitance						
Differential Mode	$C_{INDM}$			16.5		pF
Common Mode	$C_{INCM}$			33		pF
<b>OUTPUT CHARACTERISTICS</b>						
Output Voltage High	$V_{OH}$	$R_L = 10\text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	4.99	4.995		V
		$R_L = 2\text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	4.98			V
			4.96	4.98		V
			4.94			V
Output Voltage Low	$V_{OL}$	$R_L = 10\text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		5	10	mV
		$R_L = 2\text{ k}\Omega$ to $V_{CM}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$			20	mV
				20	40	mV
					60	mV
Short-Circuit Current	$I_{SC}$			$\pm 40$		mA
Closed-Loop Output Impedance	$Z_{OUT}$	$f = 1\text{ kHz}$ , $A_V = +10$		0.1		$\Omega$
<b>POWER SUPPLY</b>						
Power Supply Rejection Ratio	PSRR	$V_{SY} = 2.2\text{ V to } 5.5\text{ V}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	130	150		dB
			127			dB
Supply Current per Amplifier	$I_{SY}$	$I_O = 0\text{ mA}$ $-40^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$		1.5	1.8	mA
					2.2	mA
<b>DYNAMIC PERFORMANCE</b>						
Slew Rate	SR	$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $A_V = +1$		0.5		V/ $\mu\text{s}$
Settling Time to 0.1%	$t_s$	$V_{IN} = 4\text{ V step}$ , $R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $A_V = -1$		10		$\mu\text{s}$
Unity-Gain Crossover	UGC	$V_{IN} = 10\text{ mV p-p}$ , $R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $A_V = +1$		4		MHz
Phase Margin	$\Phi_M$	$V_{IN} = 10\text{ mV p-p}$ , $R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $A_V = +1$		57		Degrees
Gain Bandwidth Product	GBP	$V_{IN} = 10\text{ mV p-p}$ , $R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $A_V = +100$		3.4		MHz
-3 dB Closed-Loop Bandwidth	$f_{-3dB}$	$V_{IN} = 10\text{ mV p-p}$ , $R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $A_V = +1$		6.5		MHz
Overload Recovery Time		$R_L = 10\text{ k}\Omega$ , $C_L = 100\text{ pF}$ , $A_V = -10$		50		$\mu\text{s}$

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
NOISE PERFORMANCE						
Voltage Noise	$e_n$ p-p	$f = 0.1 \text{ Hz to } 10 \text{ Hz}, A_v = +100$		99		nV p-p
Voltage Noise Density	$e_n$	$f = 1 \text{ kHz}, A_v = +100$		5.9		nV/ $\sqrt{\text{Hz}}$
		$f = 1 \text{ kHz}, A_v = +100, V_{CM} = 4.5 \text{ V}$		5.3		nV/ $\sqrt{\text{Hz}}$
Current Noise	$i_n$ p-p	$f = 0.1 \text{ Hz to } 10 \text{ Hz}, A_v = +100$		10		pA p-p
Current Noise Density	$i_n$	$f = 1 \text{ kHz}, A_v = +100$		0.5		pA/ $\sqrt{\text{Hz}}$

## ABSOLUTE MAXIMUM RATINGS

Table 4.

Parameter	Rating
Supply Voltage	6 V
Input Voltage	$\pm V_{SY} \pm 0.3$ V
Input Current <sup>1</sup>	$\pm 10$ mA
Differential Input Voltage	$\pm V_{SY}$
Output Short-Circuit Duration to GND	Indefinite
Storage Temperature Range	-65°C to +150°C
Operating Temperature Range	-40°C to +125°C
Junction Temperature Range	-65°C to +150°C
Lead Temperature (Soldering, 60 sec)	300°C

<sup>1</sup> The input pins have clamp diodes to the power supply pins. Limit the input current to 10 mA or less whenever input signals exceed the power supply rail by 0.3 V.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## THERMAL RESISTANCE

$\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages using a 4-layer JEDEC board. The exposed pad of the LFCSP package is soldered to the board.

Table 5. Thermal Resistance

Package Type	$\theta_{JA}$	$\theta_{JC}$	Unit
8-Lead MSOP (RM-8)	142	45	°C/W
8-Lead LFCSP (CP-8-12)	80	14	°C/W

## ESD CAUTION



### ESD (electrostatic discharge) sensitive device.

Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

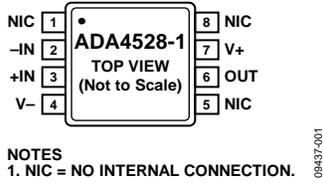


Figure 4. ADA4528-1 Pin Configuration, 8-Lead MSOP

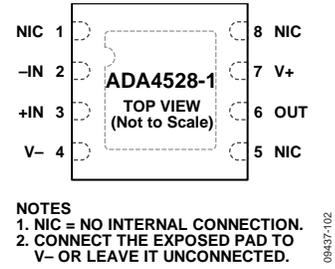


Figure 5. ADA4528-1 Pin Configuration, 8-Lead LFCSP

Table 6. ADA4528-1 Pin Function Descriptions

Pin No.	Mnemonic	Description
1, 5, 8	NIC	No Internal Connection.
2	-IN	Inverting Input.
3	+IN	Noninverting Input.
4	V-	Negative Supply Voltage.
6	OUT	Output.
7	V+	Positive Supply Voltage.
	EPAD	Exposed Pad (LFCSP Only). Connect the exposed pad to V- or leave it unconnected.



Figure 6. ADA4528-2 Pin Configuration, 8-Lead MSOP

Table 7. ADA4528-2 Pin Function Descriptions

Pin No.	Mnemonic	Description
1	OUT A	Output, Channel A.
2	-IN A	Inverting Input, Channel A.
3	+IN A	Noninverting Input, Channel A.
4	V-	Negative Supply Voltage.
5	+IN B	Noninverting Input, Channel B.
6	-IN B	Inverting Input, Channel B.
7	OUT B	Output, Channel B.
8	V+	Positive Supply Voltage.

# TYPICAL PERFORMANCE CHARACTERISTICS

T<sub>A</sub> = 25°C, unless otherwise noted.

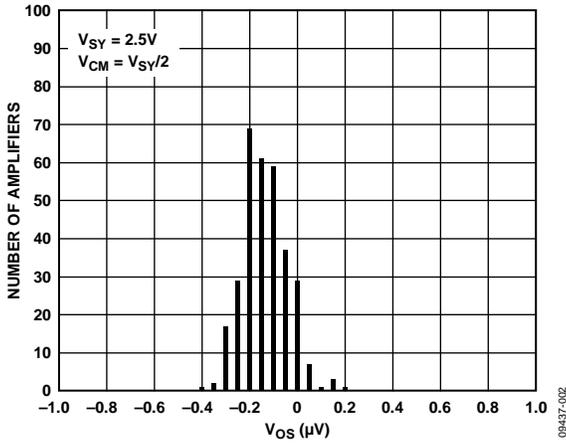


Figure 7. Input Offset Voltage Distribution

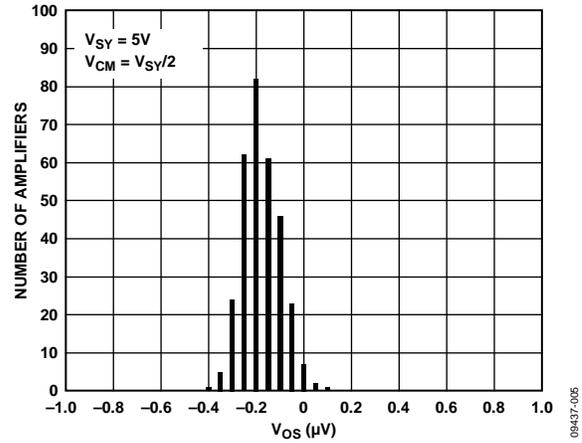


Figure 10. Input Offset Voltage Distribution

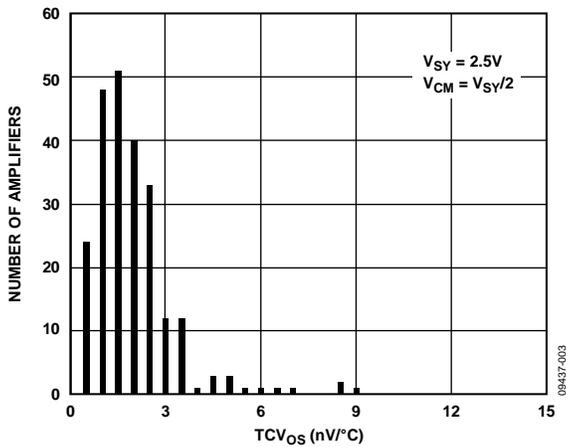


Figure 8. Input Offset Voltage Drift Distribution

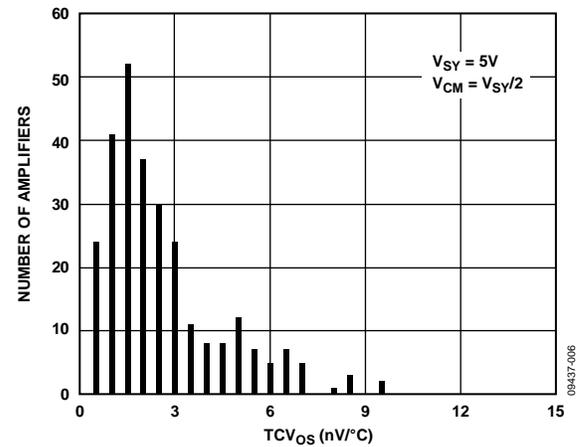


Figure 11. Input Offset Voltage Drift Distribution

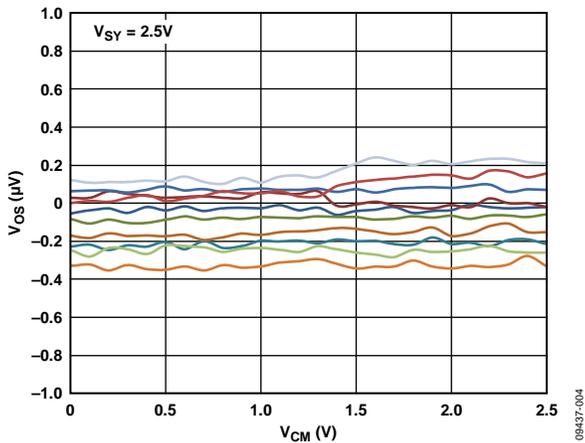


Figure 9. Input Offset Voltage vs. Common-Mode Voltage

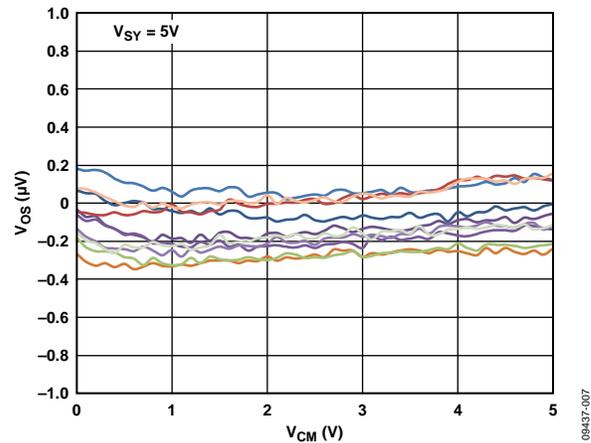


Figure 12. Input Offset Voltage vs. Common-Mode Voltage

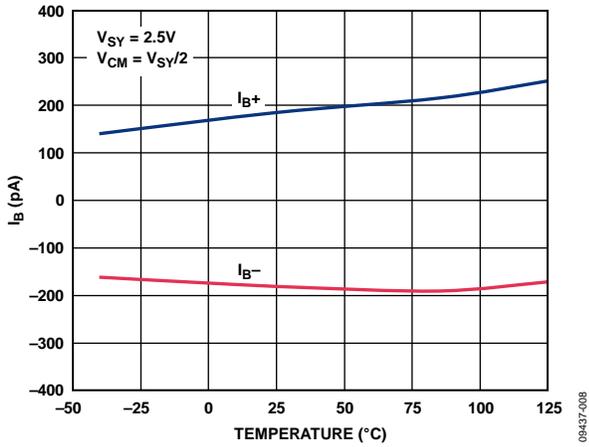


Figure 13. Input Bias Current vs. Temperature

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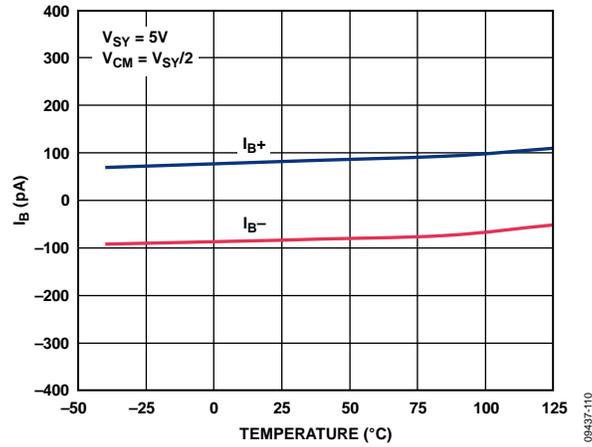


Figure 16. Input Bias Current vs. Temperature

09437-110

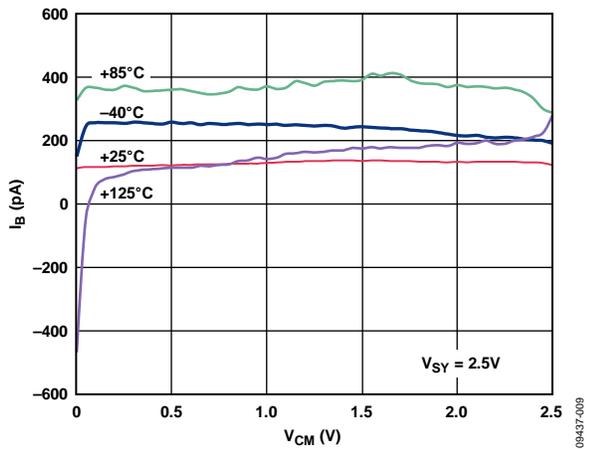


Figure 14. Input Bias Current vs. Common-Mode Voltage

09437-009

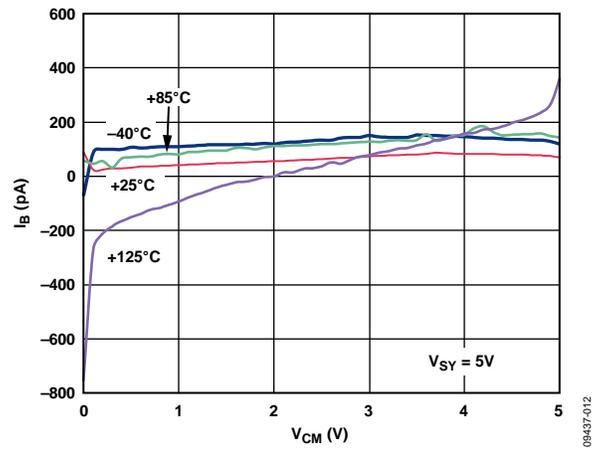


Figure 17. Input Bias Current vs. Common-Mode Voltage

09437-012

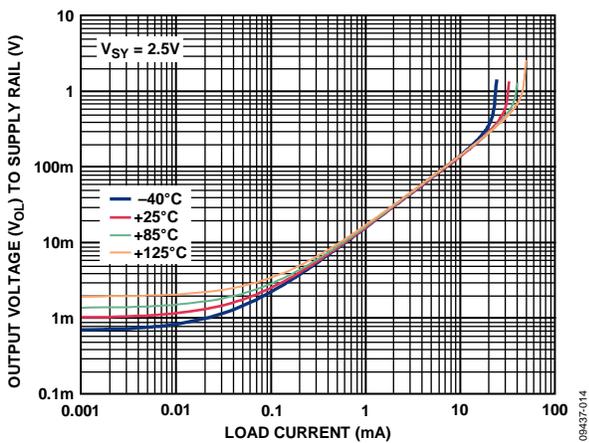


Figure 15. Output Voltage ( $V_{O1}$ ) to Supply Rail vs. Load Current

09437-014

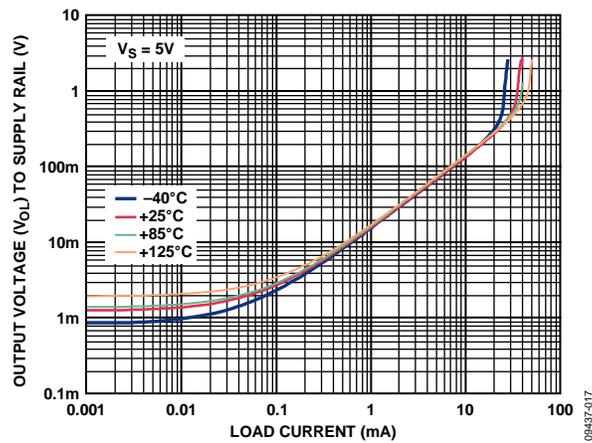


Figure 18. Output Voltage ( $V_{O1}$ ) to Supply Rail vs. Load Current

09437-017

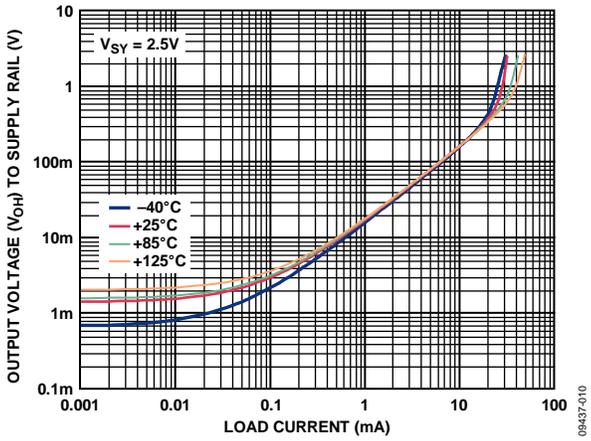


Figure 19. Output Voltage ( $V_{OH}$ ) to Supply Rail vs. Load Current

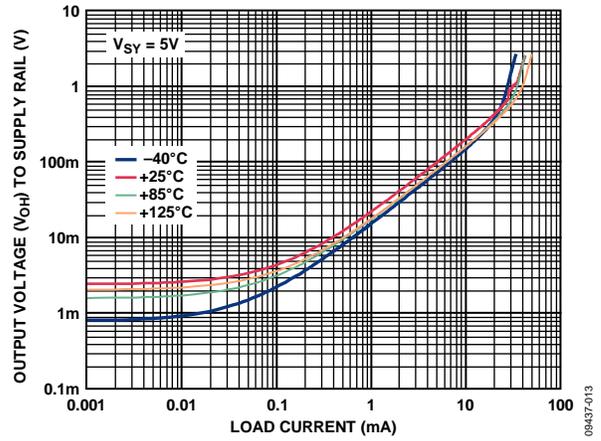


Figure 22. Output Voltage ( $V_{OH}$ ) to Supply Rail vs. Load Current

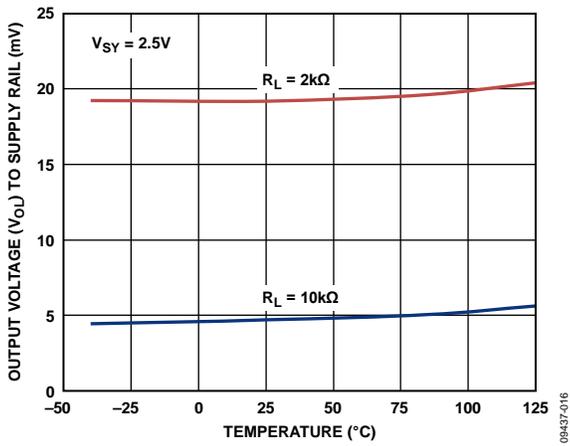


Figure 20. Output Voltage ( $V_O$ ) to Supply Rail vs. Temperature

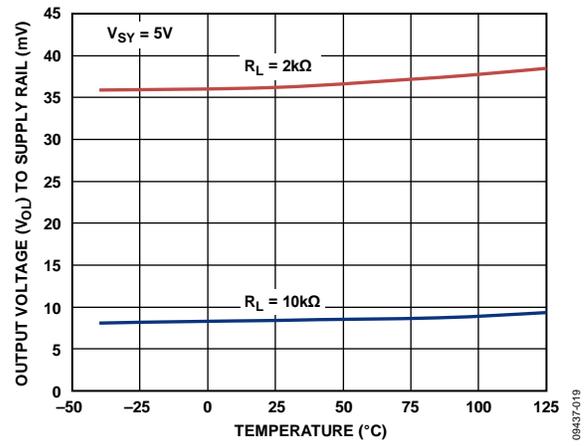


Figure 23. Output Voltage ( $V_O$ ) to Supply Rail vs. Temperature

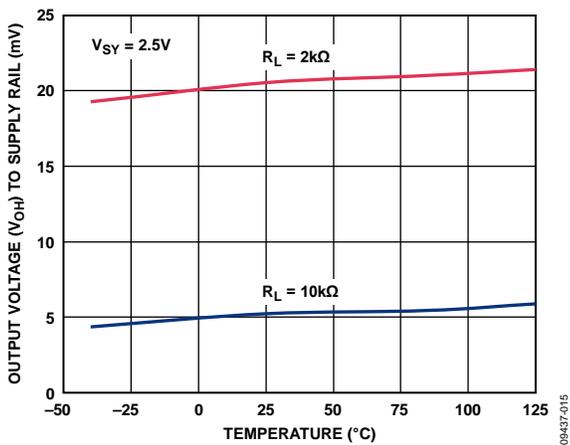


Figure 21. Output Voltage ( $V_{OH}$ ) to Supply Rail vs. Temperature

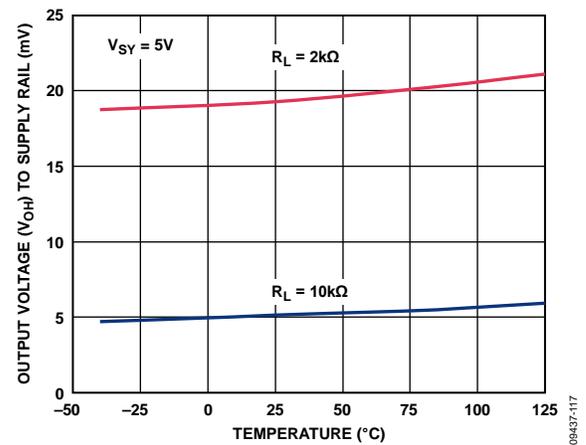


Figure 24. Output Voltage ( $V_{OH}$ ) to Supply Rail vs. Temperature

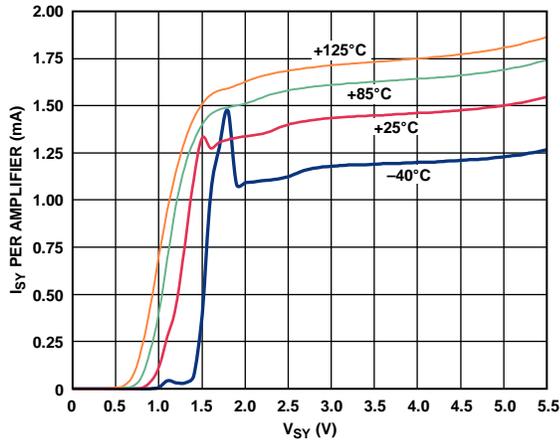


Figure 25. Supply Current vs. Supply Voltage

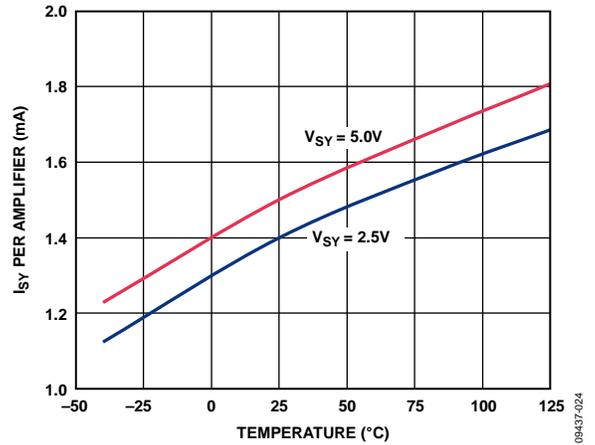


Figure 28. Supply Current vs. Temperature

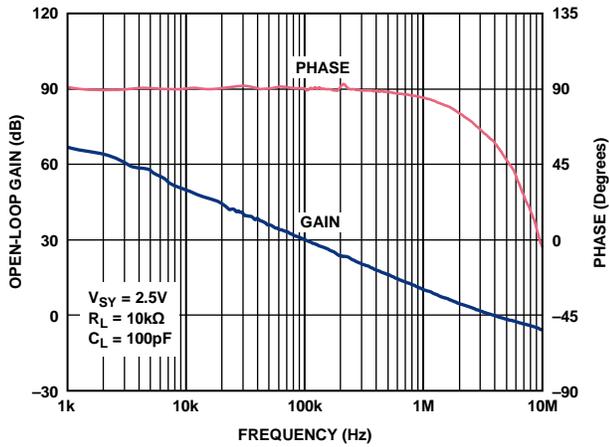


Figure 26. Open-Loop Gain and Phase vs. Frequency

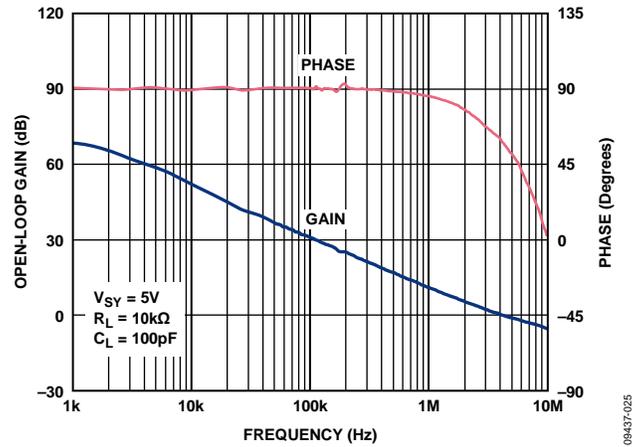


Figure 29. Open-Loop Gain and Phase vs. Frequency

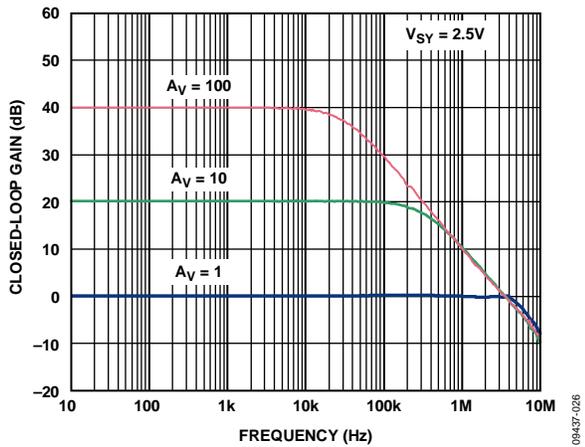


Figure 27. Closed-Loop Gain vs. Frequency

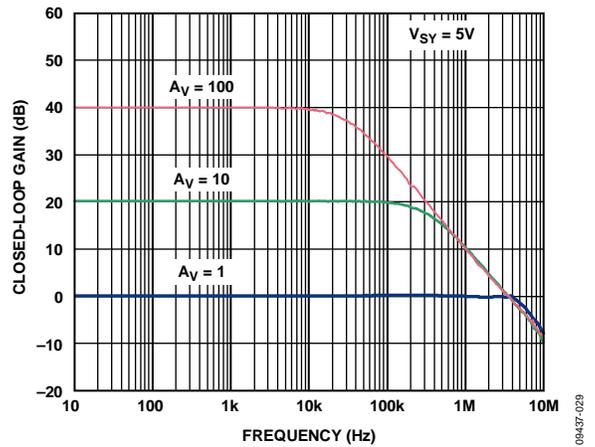


Figure 30. Closed-Loop Gain vs. Frequency

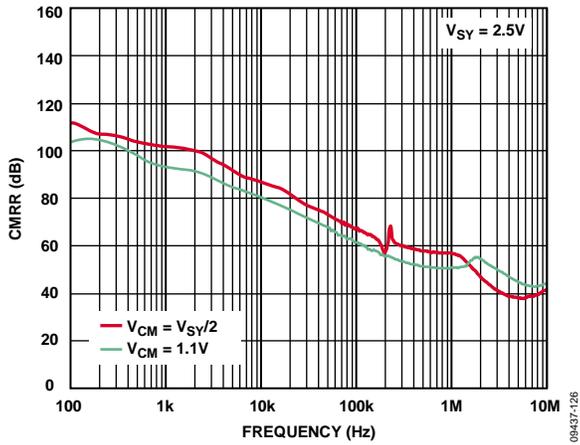


Figure 31. CMRR vs. Frequency

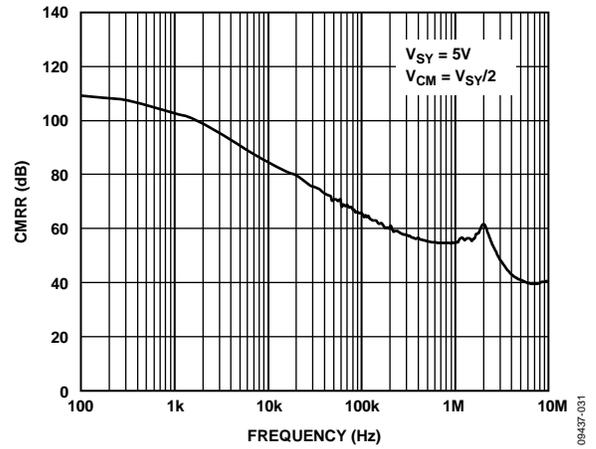


Figure 34. CMRR vs. Frequency

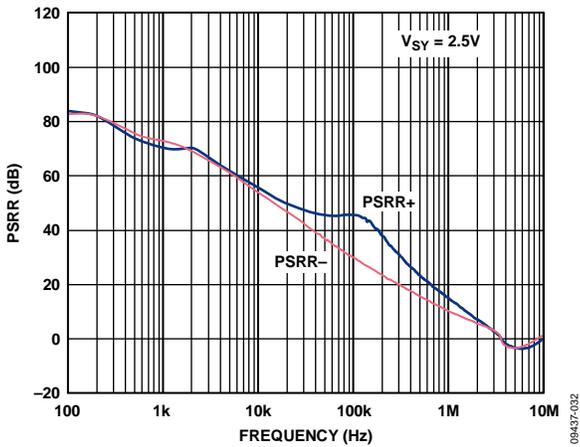


Figure 32. PSRR vs. Frequency

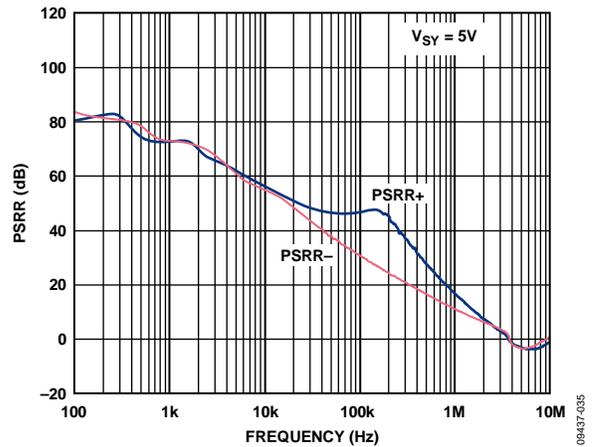


Figure 35. PSRR vs. Frequency

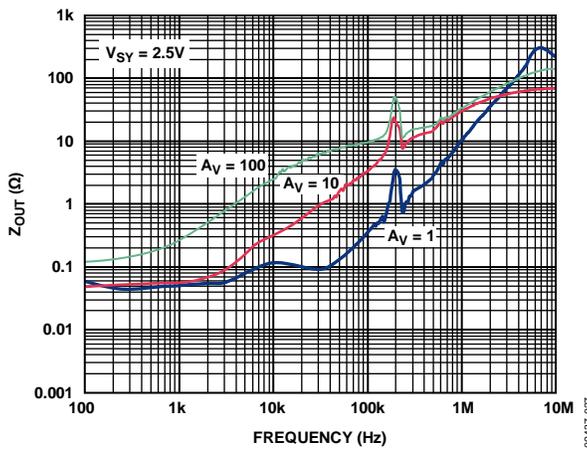


Figure 33. Output Impedance vs. Frequency

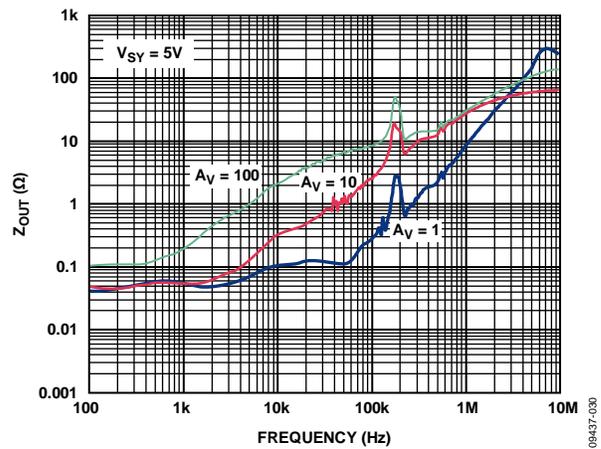


Figure 36. Output Impedance vs. Frequency

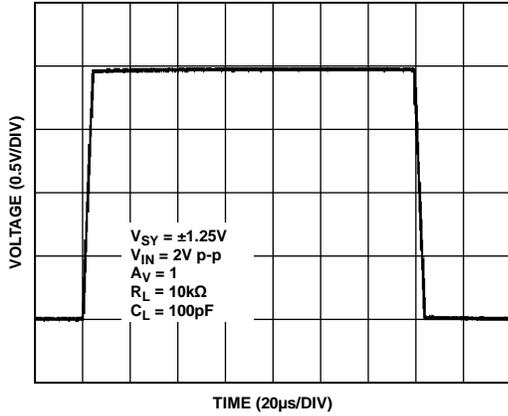


Figure 37. Large Signal Transient Response

09437-034

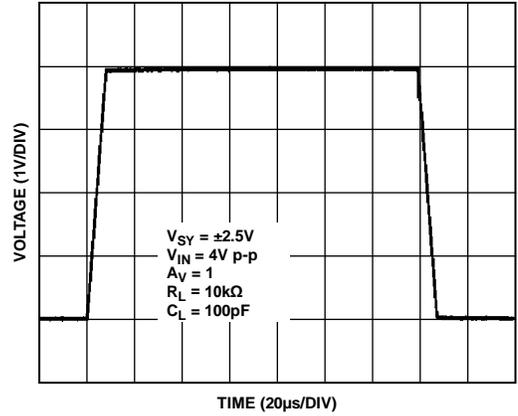


Figure 40. Large Signal Transient Response

09437-037

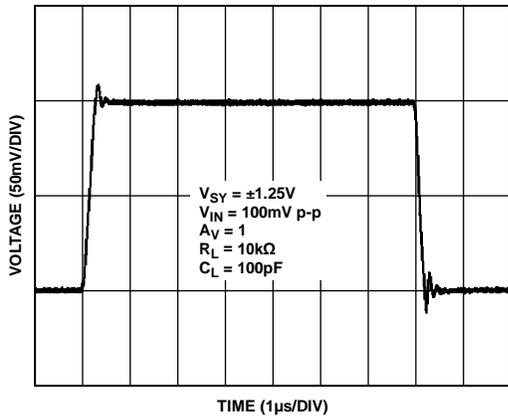


Figure 38. Small Signal Transient Response

09437-038

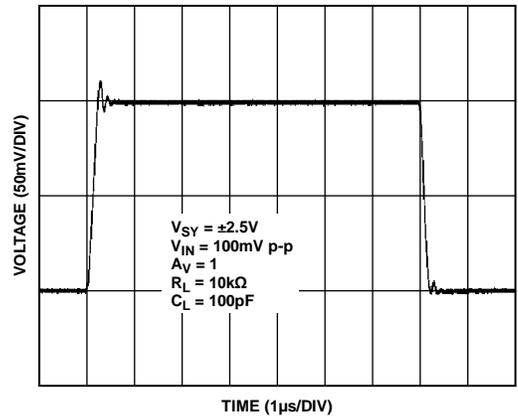


Figure 41. Small Signal Transient Response

09437-041

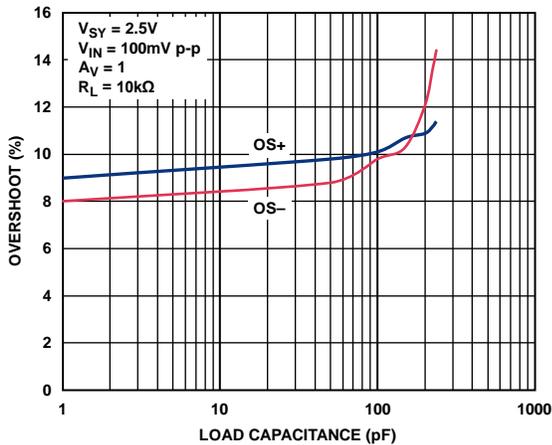


Figure 39. Small Signal Overshoot vs. Load Capacitance

09437-033

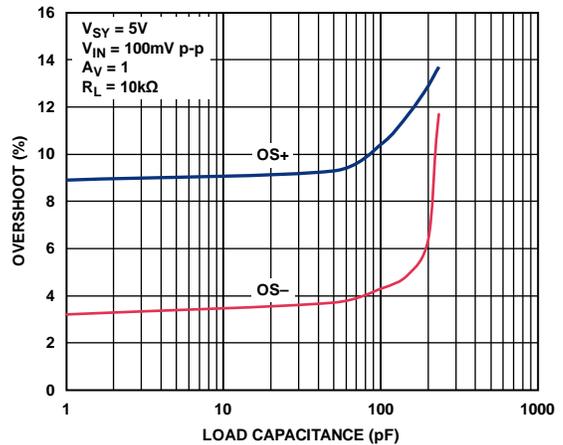


Figure 42. Small Signal Overshoot vs. Load Capacitance

09437-036

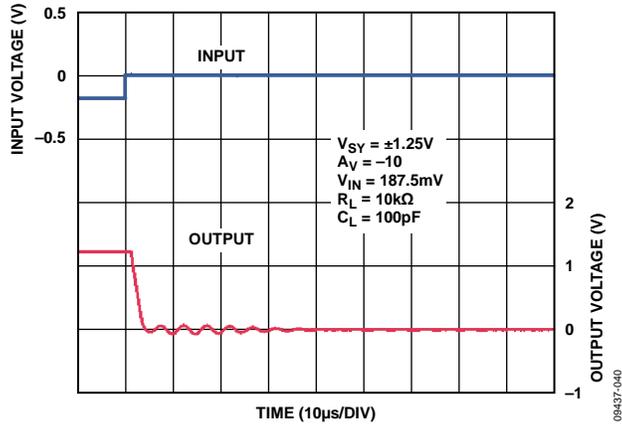


Figure 43. Positive Overload Recovery

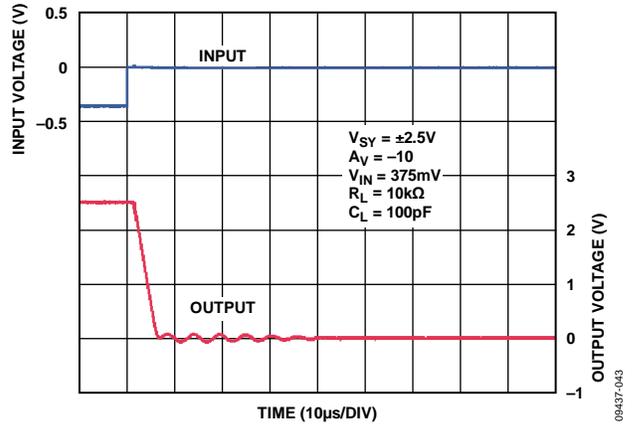


Figure 46. Positive Overload Recovery

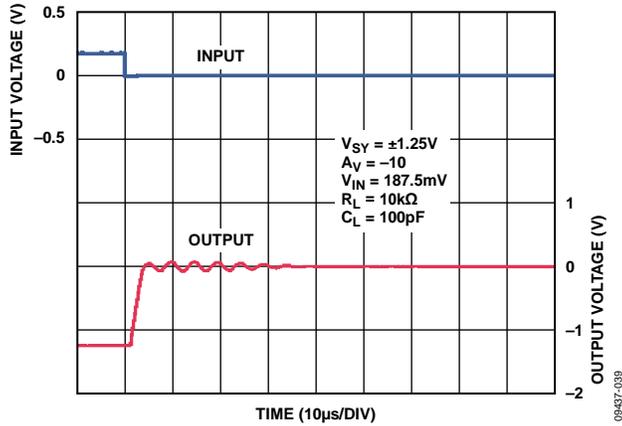


Figure 44. Negative Overload Recovery

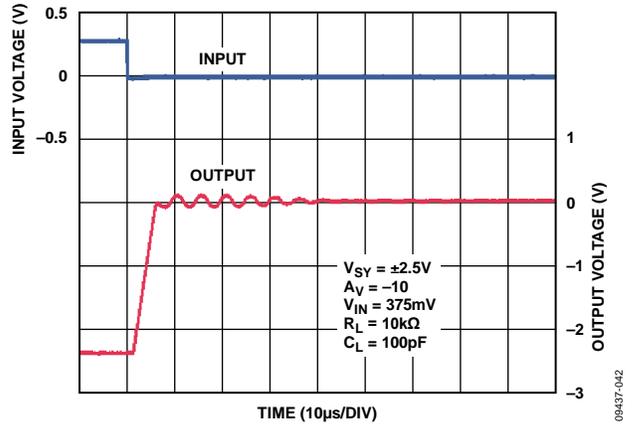


Figure 47. Negative Overload Recovery

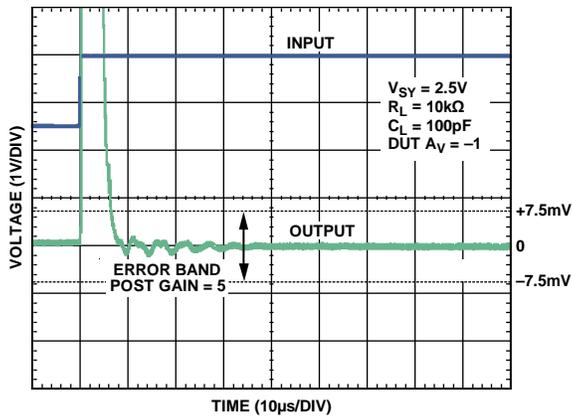


Figure 45. Positive Settling Time to 0.1%

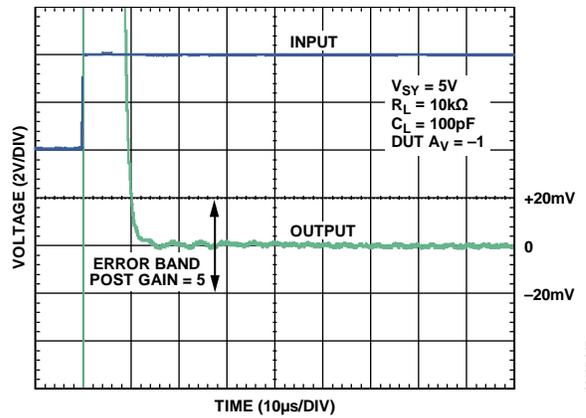


Figure 48. Positive Settling Time to 0.1%

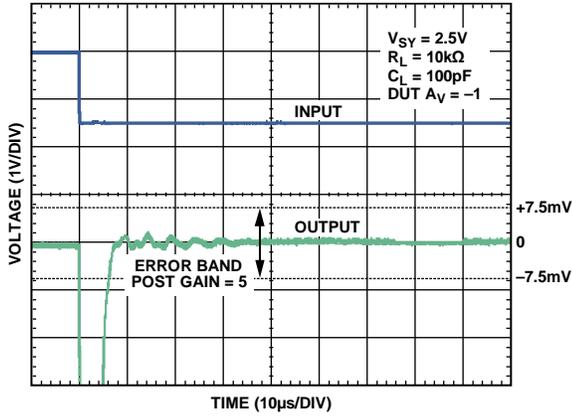


Figure 49. Negative Settling Time to 0.1%

09437-045

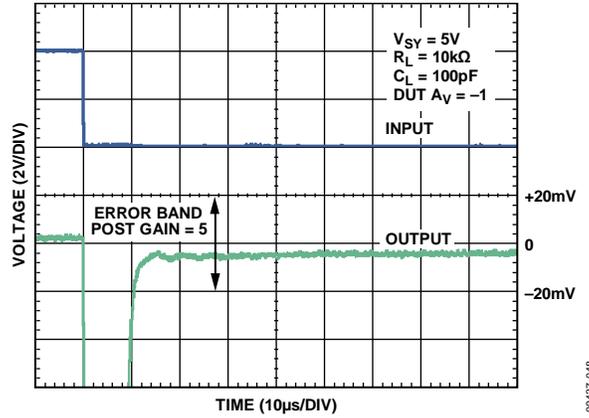


Figure 52. Negative Settling Time to 0.1%

09437-048

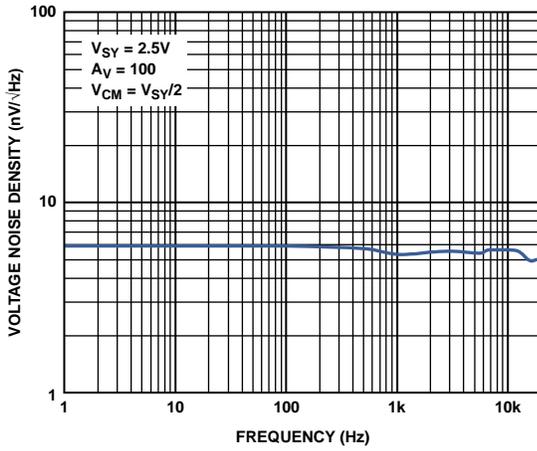


Figure 50. Voltage Noise Density vs. Frequency

09437-046

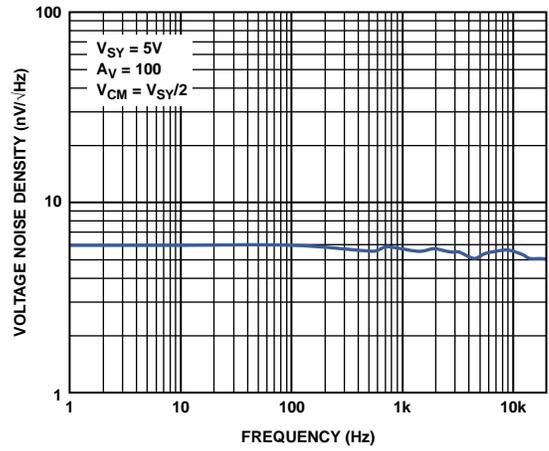


Figure 53. Voltage Noise Density vs. Frequency

09437-049

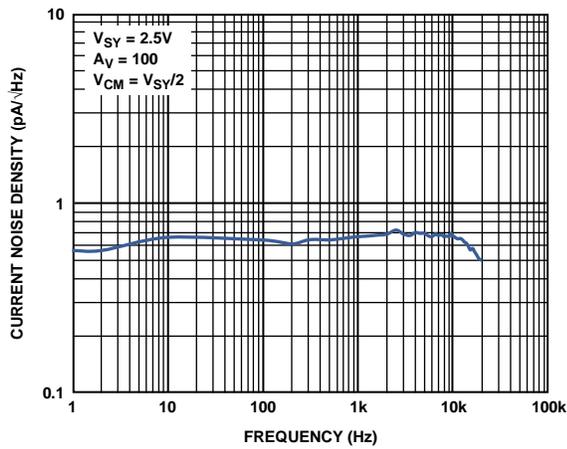


Figure 51. Current Noise Density vs. Frequency

09437-150

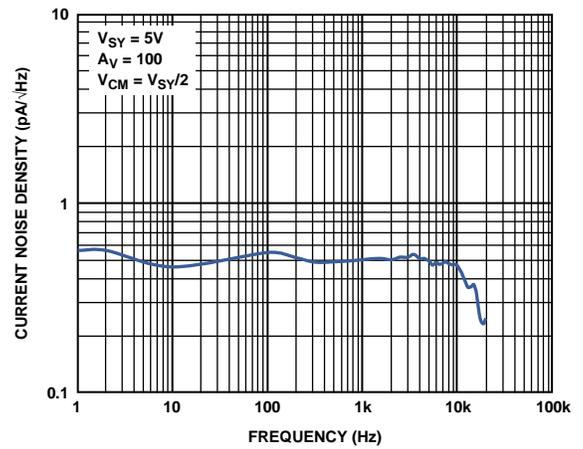


Figure 54. Current Noise Density vs. Frequency

09437-153

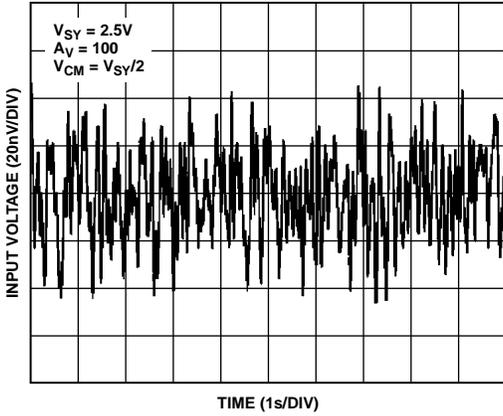


Figure 55. 0.1 Hz to 10 Hz Noise

09437-050

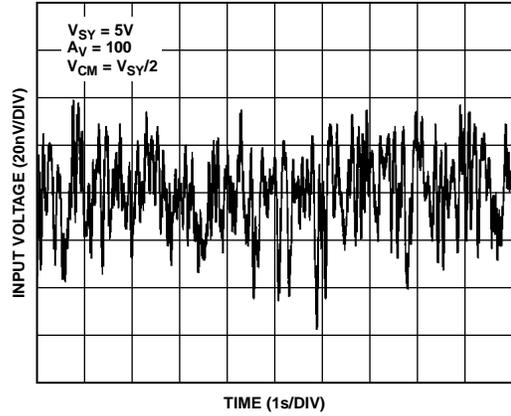


Figure 58. 0.1 Hz to 10 Hz Noise

09437-053

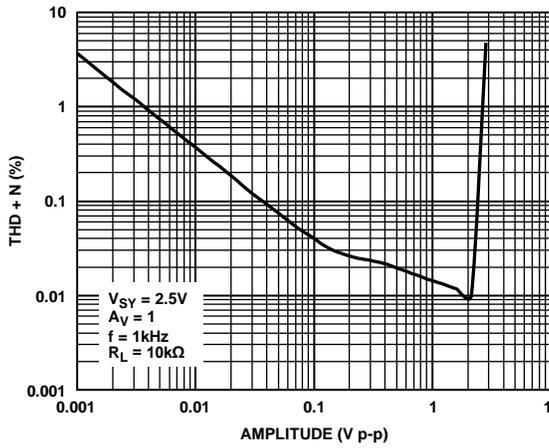


Figure 56. THD + N vs. Amplitude

09437-152

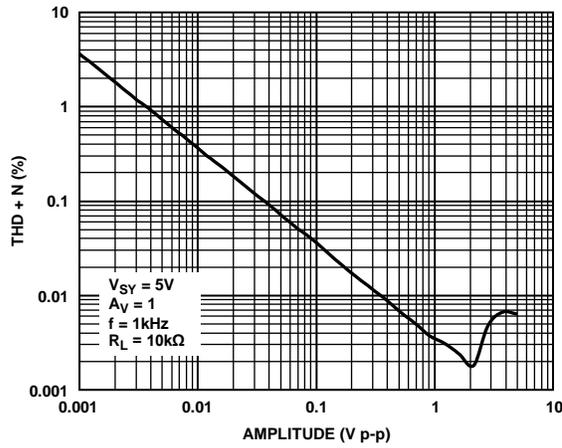


Figure 59. THD + N vs. Amplitude

09437-155

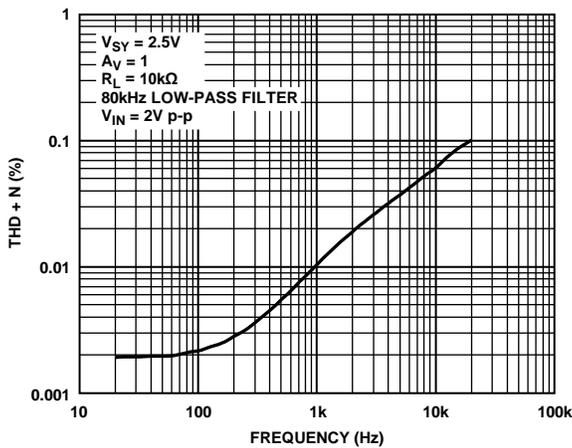


Figure 57. THD + N vs. Frequency

09437-056

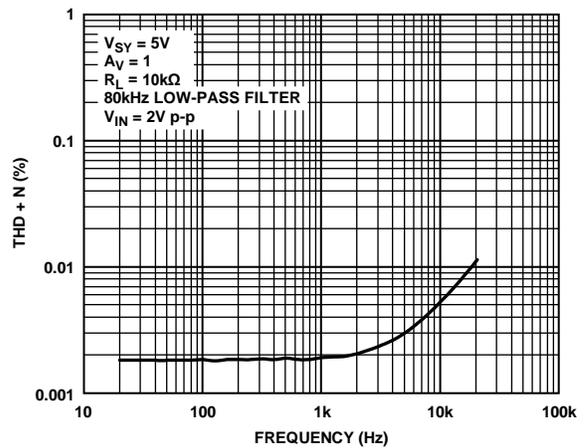


Figure 60. THD + N vs. Frequency

09437-057

## APPLICATIONS INFORMATION

The ADA4528-1/ADA4528-2 are precision, ultralow noise, zero-drift operational amplifiers that feature a patented chopping technique. This chopping technique offers ultralow input offset voltage of 0.3  $\mu\text{V}$  typical and input offset voltage drift of 0.002  $\mu\text{V}/^\circ\text{C}$  typical.

Offset voltage errors due to common-mode voltage swings and power supply variations are also corrected by the chopping technique, resulting in a typical CMRR figure of 158 dB and a PSRR figure of 150 dB at 2.5 V supply voltage. The ADA4528-1/ADA4528-2 have low broadband noise of 5.6  $\text{nV}/\sqrt{\text{Hz}}$  (at  $f = 1 \text{ kHz}$ ,  $A_V = +100$ , and  $V_{\text{SY}} = 2.5 \text{ V}$ ) with no  $1/f$  noise component. These features are ideal for amplification of low level signals in dc or subhertz high precision applications.

For more information about the chopper architecture of the ADA4528-1/ADA4528-2, see the [AN-1114 Application Note, Lowest Noise Zero-Drift Amplifier Has 5.6  \$\text{nV}/\sqrt{\text{Hz}}\$  Voltage Noise Density](#).

### INPUT PROTECTION

The ADA4528-1/ADA4528-2 have internal ESD protection diodes that are connected between the inputs and each supply rail. These diodes protect the input transistors in the event of electrostatic discharge and are reverse biased during normal operation. This protection scheme allows voltages as high as approximately 300 mV beyond the rails to be applied at the input of either terminal without causing permanent damage (see Table 4 in the Absolute Maximum Ratings section).

When either input exceeds one of the supply rails by more than 300 mV, the ESD diodes become forward biased and large amounts of current begin to flow through them. Without current limiting, this excessive fault current causes permanent damage to the device.

If the inputs will be subjected to overvoltage conditions, insert a resistor in series with each input to limit the input current to 10 mA maximum. However, consider the resistor thermal noise effect on the entire circuit.

For example, at a 5 V supply voltage, the broadband voltage noise of the ADA4528-1/ADA4528-2 is approximately 6  $\text{nV}/\sqrt{\text{Hz}}$  (at unity gain). A 1 k $\Omega$  resistor has thermal noise of 4  $\text{nV}/\sqrt{\text{Hz}}$ . Adding a 1 k $\Omega$  resistor at the noninverting input pin increases the total noise by 30% root sum square (rss).

### RAIL-TO-RAIL INPUT AND OUTPUT

The ADA4528-1/ADA4528-2 feature rail-to-rail input and output with a supply voltage from 2.2 V to 5.5 V. Figure 61 shows the input and output waveforms of the ADA4528-1/ADA4528-2 configured as a unity-gain buffer with a supply voltage of  $\pm 2.5 \text{ V}$  and a resistive load of 10 k $\Omega$ . With an input voltage of  $\pm 2.5 \text{ V}$ , the ADA4528-1/ADA4528-2 allow the output to swing very close to both rails. Additionally, the parts do not exhibit phase reversal.

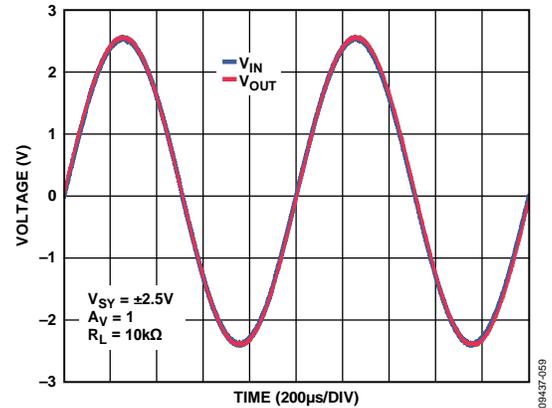


Figure 61. Rail-to-Rail Input and Output

### NOISE CONSIDERATIONS

For more information about the noise characteristics of the ADA4528-1/ADA4528-2, see the [AN-1114 Application Note, Lowest Noise Zero-Drift Amplifier Has 5.6  \$\text{nV}/\sqrt{\text{Hz}}\$  Voltage Noise Density](#).

#### 1/f Noise

$1/f$  noise, also known as pink noise or flicker noise, is inherent in semiconductor devices and increases as frequency decreases. At low frequency,  $1/f$  noise is a major noise contributor and causes a significant output voltage offset when amplified by the noise gain of the circuit. However, the ADA4528-1/ADA4528-2 eliminate the  $1/f$  noise internally, thus making these parts an excellent choice for dc or subhertz high precision applications. The 0.1 Hz to 10 Hz amplifier voltage noise is only 97 nV p-p ( $A_V = +100$ ) at a supply voltage of 2.5 V.

The low frequency  $1/f$  noise, which appears as a slow varying offset to the ADA4528-1/ADA4528-2, is greatly reduced by the chopping technique. This reduction in  $1/f$  noise allows the ADA4528-1/ADA4528-2 to have much lower noise at dc and low frequency compared to standard low noise amplifiers that are susceptible to  $1/f$  noise. Figure 50 and Figure 53 show the voltage noise density of the amplifier with no  $1/f$  noise.

**Source Resistance**

With 5.6 nV/√Hz of broadband noise at 1 kHz ( $V_{SY} = 2.5\text{ V}$  and  $A_V = +100$ ), the ADA4528-1/ADA4528-2 are among the lowest noise zero-drift amplifiers currently available in the industry. Therefore, it is important to carefully select the input source resistance to maintain a total low noise.

The total input referred broadband noise ( $e_n\text{ total}$ ) from any amplifier is primarily a function of three types of noise: input voltage noise, input current noise, and thermal (Johnson) noise from the external resistors.

These uncorrelated noise sources can be summed up in a root sum squared (rss) manner using the following equation:

$$e_n\text{ total} = [e_n^2 + 4kTR_S + (i_n \times R_S)^2]^{1/2}$$

where:

$e_n$  is the input voltage noise of the amplifier (V/√Hz).

$k$  is the Boltzmann's constant ( $1.38 \times 10^{-23}\text{ J/K}$ ).

$T$  is the temperature in Kelvin (K).

$R_S$  is the total input source resistance ( $\Omega$ ).

$i_n$  is the input current noise of the amplifier (A/√Hz).

The total equivalent rms noise over a specific bandwidth is expressed as

$$e_{n,rms} = e_n\text{ total} \times \sqrt{BW}$$

where  $BW$  is the bandwidth in hertz.

This analysis is valid for broadband noise calculation. If the bandwidth of concern includes the chopping frequency, more complicated calculations must be made to include the effect of the noise energy spectrum at the chopping frequency (see the Residual Voltage Ripple section).

With a low source resistance of  $R_S < 1\text{ k}\Omega$ , the voltage noise of the amplifier dominates. As source resistance increases, the thermal noise of  $R_S$  dominates. As the source resistance increases further, where  $R_S > 100\text{ k}\Omega$ , the current noise becomes the main contributor to the total input noise. A good selection table for low noise op amps can be found in the AN-940 Application Note, *Low Noise Amplifier Selection Guide for Optimal Noise Performance*.

**Voltage Noise Density with Different Gain Configurations**

Figure 62 shows the voltage noise density vs. closed-loop gain of a zero-drift amplifier from a leading competitor. The voltage noise density of the amplifier increases from 11 nV/√Hz to 21 nV/√Hz as the closed-loop gain decreases from 1000 to 1.

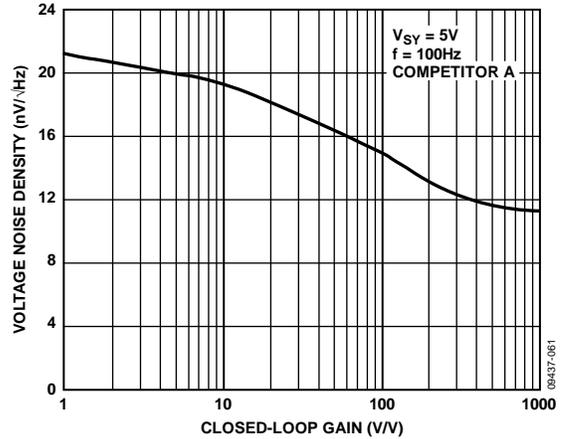


Figure 62. Competitor A: Voltage Noise Density vs. Closed-Loop Gain

Figure 63 shows the voltage noise density vs. frequency of the ADA4528-1/ADA4528-2 for three different gain configurations. The ADA4528-1/ADA4528-2 offer a constant input voltage noise density of 6 nV/√Hz to 7 nV/√Hz, regardless of the gain configuration.

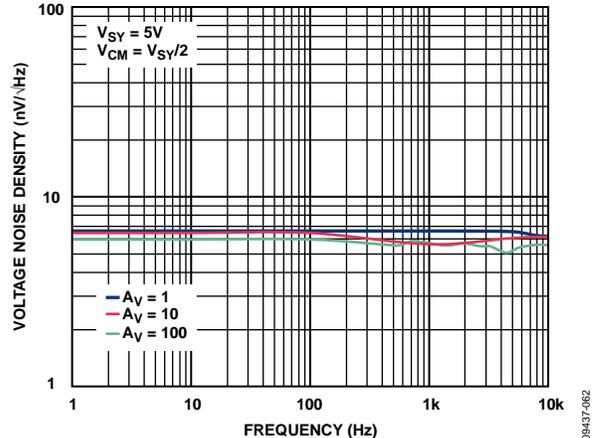


Figure 63. Voltage Noise Density vs. Frequency with Different Gain Configurations

**Residual Voltage Ripple**

Although autocorrection feedback (ACFB) suppresses the chopping related voltage ripple, higher noise spectrum exists at the chopping frequency and its harmonics due to the remaining ripple. Figure 64 shows the voltage noise density of the ADA4528-1/ADA4528-2 configured in unity gain. A noise energy spectrum of 50 nV/√Hz can be seen at the chopping frequency of 200 kHz. This noise energy spectrum is significant when the op amp has a closed-loop frequency that is higher than the chopping frequency.

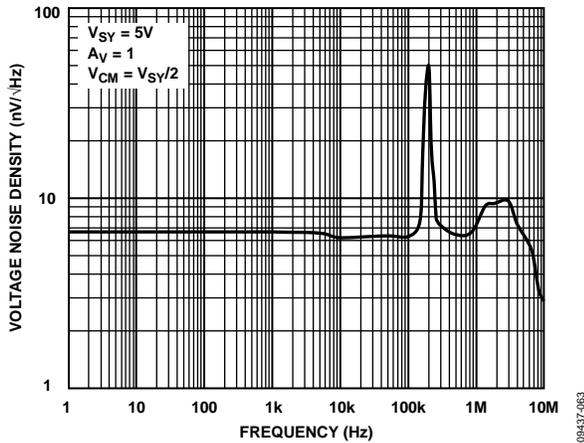


Figure 64. Voltage Noise Density vs. Frequency

To further suppress the noise at the chopping frequency, it is recommended that a post filter be placed at the output of the amplifier. For more information about residual voltage ripple, see the AN-1114 Application Note, *Lowest Noise Zero-Drift Amplifier Has 5.6 nV/√Hz Voltage Noise Density*.

**COMPARATOR OPERATION**

Figure 65 shows the ADA4528-1 configured as a voltage follower with an input voltage that is always kept at midpoint of the power supplies. A1 and A2 indicate the placement of ammeters to measure supply current. As shown in Figure 66, in normal operating condition,  $I_{SY+} = I_{SY-} = 1.5$  mA per amplifier with 5 V of supplies.

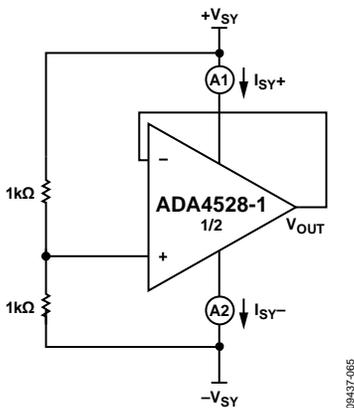


Figure 65. Voltage Follower

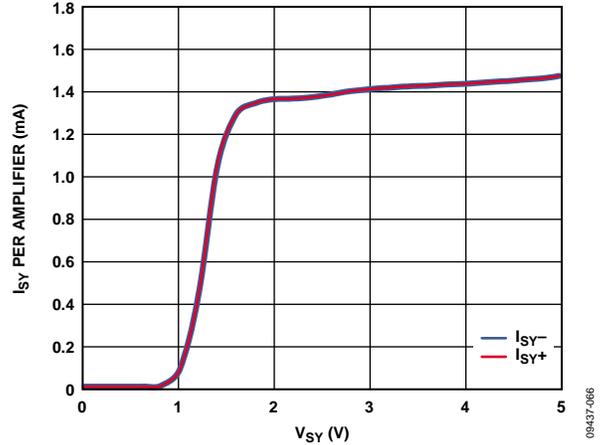


Figure 66. Supply Current vs. Supply Voltage (Voltage Follower)

Figure 67 and Figure 68 show the ADA4528-1 configured as comparators, with 1kΩ resistors in series with the input pins. Figure 69 shows the supply currents for both configurations. Supply currents do not change significantly, where  $I_{SY+} = I_{SY-} = 1.5$  mA per amplifier at 5 V of supplies.

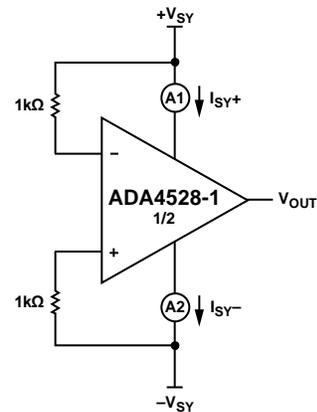


Figure 67. Comparator A

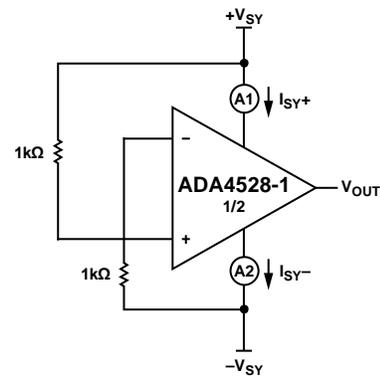


Figure 68. Comparator B

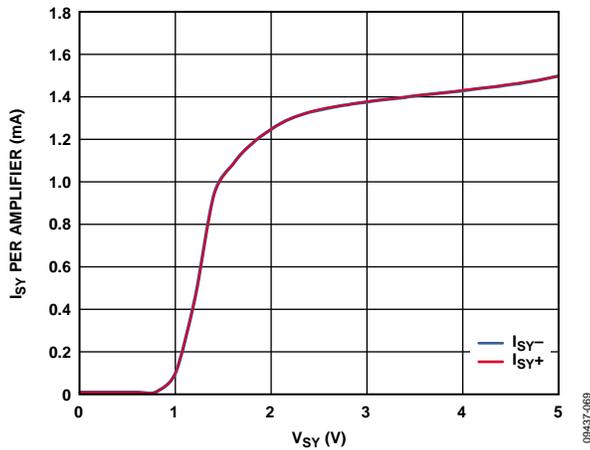


Figure 69. Supply Current vs. Supply Voltage (Comparator A and Comparator B)

For more details on op amps as comparators, refer to the [AN-849 Application Note, Using Op Amps as Comparators](#).

**PRINTED CIRCUIT BOARD LAYOUT**

The ADA4528-1/ADA4528-2 are high precision devices with ultralow offset voltage and noise. Therefore, care must be taken in the design of the printed circuit board (PCB) layout to achieve the optimum performance of the ADA4528-1/ADA4528-2 at board level.

To avoid leakage currents, keep the surface of the board clean and free of moisture. Coating the board surface creates a barrier to moisture accumulation and reduces parasitic resistance on the board.

To minimize power supply disturbances caused by output current variation, properly bypass the power supplies and keep the supply traces short. Connect bypass capacitors as close as possible to the device supply pins.

Stray capacitances are a concern at the outputs and the inputs of the amplifier. It is recommended that signal traces be kept at a distance of at least 5 mm from supply lines to minimize coupling.

A potential source of offset error is the Seebeck voltage on the circuit board. The Seebeck voltage occurs at the junction of two dissimilar metals and is a function of the temperature of the

junction. The most common metallic junctions on a circuit board are solder-to-board trace and solder-to-component lead.

Figure 70 shows a cross section of a surface-mount component soldered to a PCB. A variation in temperature across the board (where  $T_{A1} \neq T_{A2}$ ) causes a mismatch in the Seebeck voltages at the solder joints, thereby resulting in thermal voltage errors that degrade the ultralow offset voltage performance of the ADA4528-1/ADA4528-2.

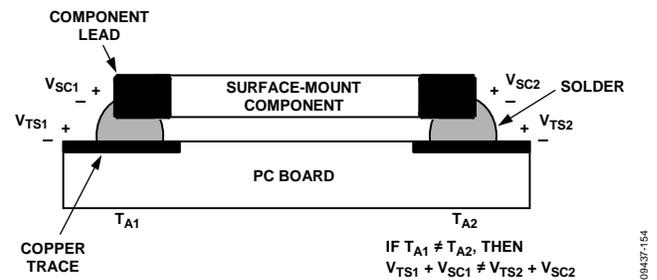
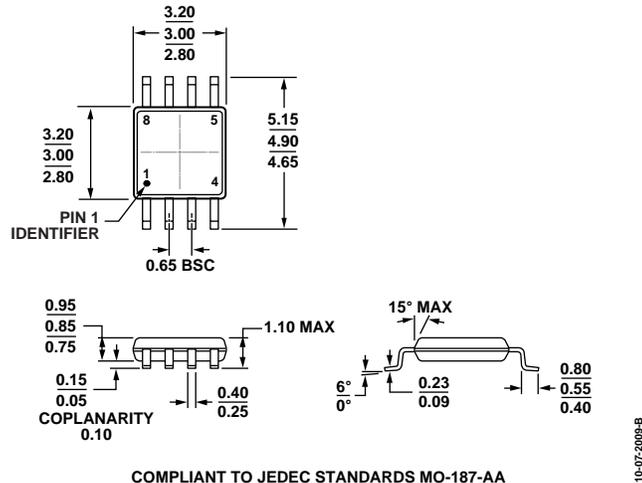


Figure 70. Mismatch in Seebeck Voltages Causes Seebeck Voltage Error

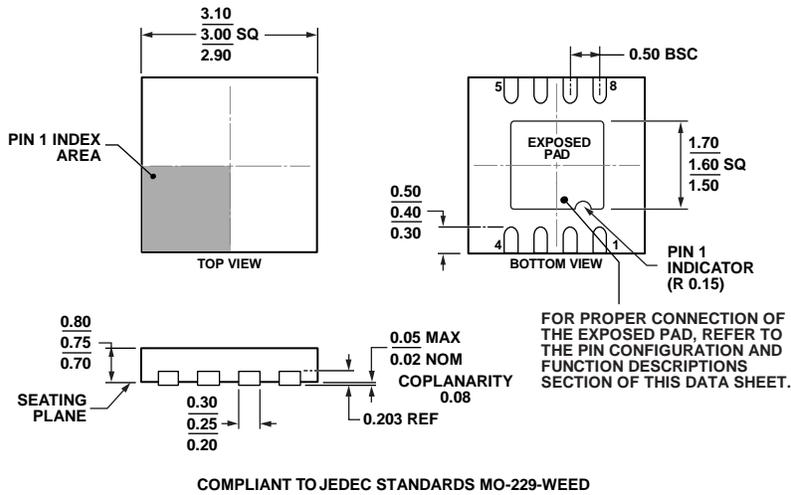
To minimize these thermocouple effects, orient resistors so that heat sources warm both ends equally. Where possible, the input signal paths should contain matching numbers and types of components to match the number and type of thermocouple junctions. For example, dummy components, such as zero value resistors, can be used to match the thermoelectric error source (real resistors in the opposite input path). Place matching components in close proximity and orient them in the same manner to ensure equal Seebeck voltages, thus canceling thermal errors. Additionally, use leads of equal length to keep thermal conduction in equilibrium. Keep heat sources on the PCB as far away from the amplifier input circuitry as practical.

It is highly recommended that a ground plane be used. A ground plane helps to distribute heat throughout the board, maintains a constant temperature across the board, and reduces EMI noise pickup.

# OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-187-AA  
 Figure 71. 8-Lead Mini Small Outline Package [MSOP]  
 (RM-8)  
 Dimensions shown in millimeters



COMPLIANT TO JEDEC STANDARDS MO-229-WEED  
 Figure 72. 8-Lead Lead Frame Chip Scale Package [LF CSP\_WD]  
 3 mm x 3 mm Body, Very Very Thin, Dual Lead  
 (CP-8-12)  
 Dimensions shown in millimeters

## ORDERING GUIDE

Model <sup>1</sup>	Temperature Range	Package Description	Package Option	Branding
ADA4528-1ARMZ	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	A2R
ADA4528-1ARMZ-R7	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	A2R
ADA4528-1ARMZ-RL	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	A2R
ADA4528-1ACPZ-R7	-40°C to +125°C	8-Lead Lead Frame Chip Scale Package [LF CSP_WD]	CP-8-12	A2R
ADA4528-1ACPZ-RL	-40°C to +125°C	8-Lead Lead Frame Chip Scale Package [LF CSP_WD]	CP-8-12	A2R
ADA4528-2ARMZ	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	A32
ADA4528-2ARMZ-R7	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	A32
ADA4528-2ARMZ-RL	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	A32

<sup>1</sup> Z = RoHS Compliant Part.

NOTES